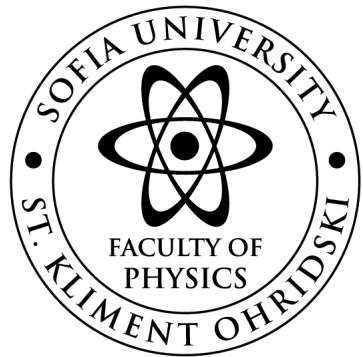




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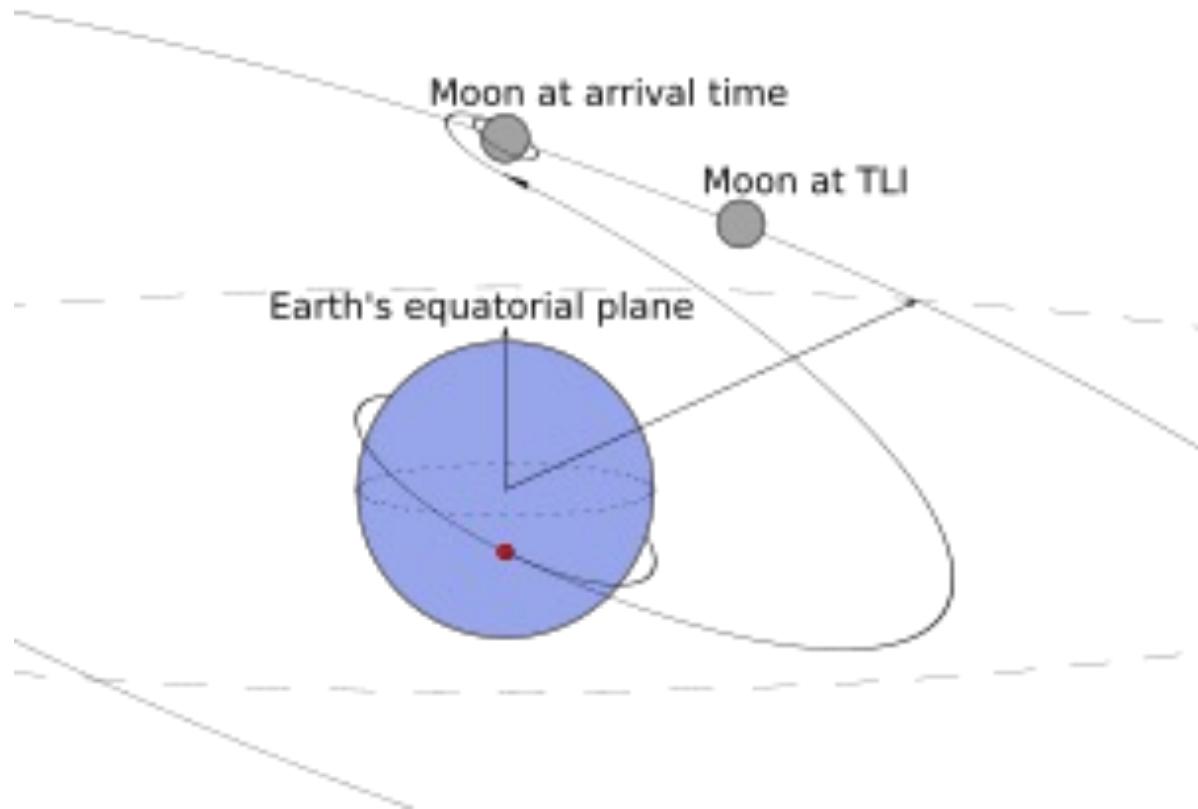
ORBITAL DYNAMICS AND ORBITAL DESIGN – LAMBERT’S PROBLEM

Michael Caneff

Problem Overview

Initial Conditions:

- Arrive at a lunar orbit on October 28th with a ± 1 day budget
- 8.2 km/s total allotted delta V velocity budget
- *Original Parking Orbit*: $a = 15\ 600\ km$, $e = 0.2$, $i = 75^\circ$, $RAAN = 0$, $\omega = 0$, $\nu = 0$
- *Final Parking orbit*: $a = 5\ 500\ km$, $e = 0.2$, $i = 110^\circ$



Lamberts Problem - Overview

Lambert's problem asks:

Given two points in space, P_1 and P_2 , under the influence of a gravitational field with parameter μ , and a transfer time ΔT ,

Can we determine a unique solution the Keplerian elements of an orbit that connects these points?

If this is possible then:

1. Orbit Determination - what are the Keplerian Elements of an orbit
2. Targeting (two objects reaching the same point in space and time)
3. Rendezvous (two objects reaching the same point in same, time and **velocity**)

Hint.. It is!

(But its not a unique solution)

Given only P_1 , P_2 , and ΔT . Only the SMA is the required variable necessary to solve for.

From which we can determine e , i , w , RAAN, TA following this getting the velocity at this point is trivial



Pauca sed matura (Few, but ripe)



Historical Context:

- **Johann Heinrich Lambert** first posed Lambert's Problem in **1761**, formulating the question of determining an orbit given two positions and a time of flight. However, he did not provide a rigorous proof.
- **Joseph-Louis Lagrange** (late 18th century) later analyzed the problem and contributed to its theoretical foundation, but gave no practical solution
- It was **Carl Friedrich Gauss** in **1809** who developed a complete numerical method to solve the problem, correctly predicting the orbital path of “1 Ceres”

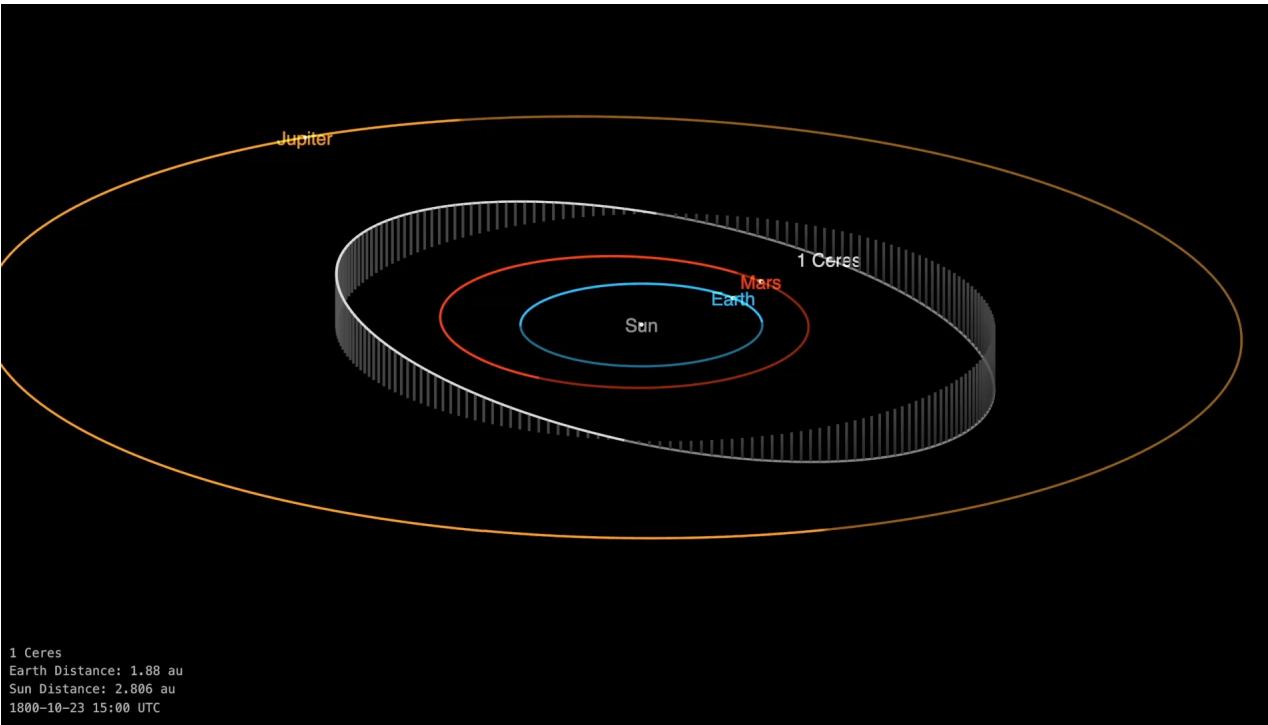


Figure: Position of planets at the time of Gauss 1809

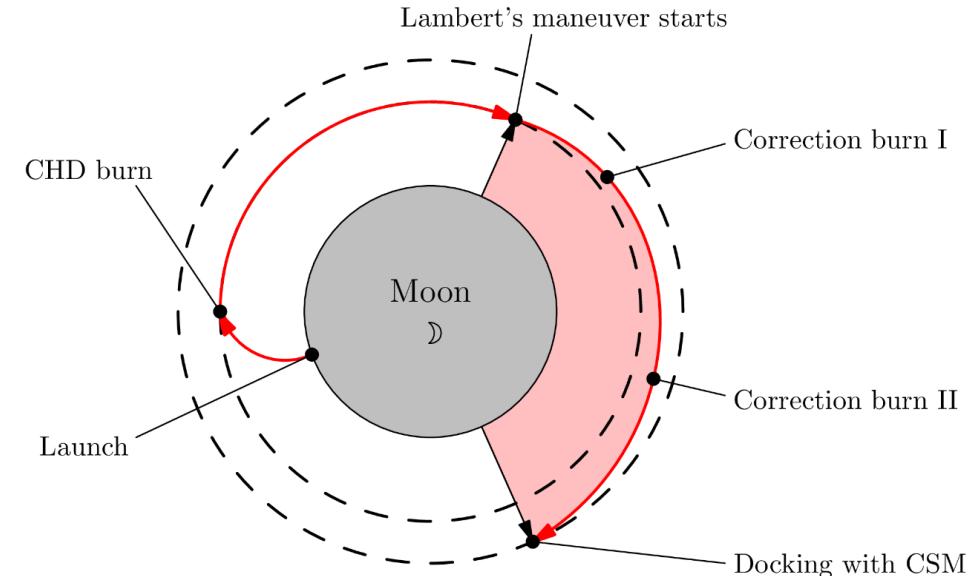


Historical Context:

- The first modern algorithms of Lambert's problem were employed in the 1950s and are currently being developed today. Still an open research question
- Used in the Apollo missions to make the rendezvous with the CSM (Command and Service Module) – reportedly taking 15-30min to perform this calculation

```
# INPUT
# (1) RINIT INITIAL POSITION RADIUS VECTOR
# (2) VINIT INITIAL POSITION VELOCITY VECTOR
# (3) RTARG TARGET POSITION RADIUS VECTOR
# (4) DELLT4 DESIRED TIME OF FLIGHT FROM RINIT TO RTARG
# (5) INTIME TIME OF RINIT
# (6) 0D NUMBER OF ITERATIONS OF LAMBERT/INTEGRVS
# (7) 2D ANGLE TO 180 DEGREES WHEN ROTATION STARTS
# (8) RTX1 -2 FOR EARTH, -10D FOR LUNAR
# (9) RTX2 COORDINATE SYSTEM ORIGIN -- 0 FOR EARTH, 2 FOR LUNAR
# PUSHLOC SET AT 4D
#
# Page 487
# OUTPUT
# (1) RTARG OFFSET TARGET POSITION VECTOR
# (2) VIPRIME MANEUVER VELOCITY REQUIRED
# (3) VTPRIME VELOCITY AT TARGET AFTER MANEUVER
# (4) DELVEET3 DELTA VELOCITY REQUIRED FOR MANEUVER
```

<https://github.com/chrislgarry/Apollo-11>



```
# COMPUTE THE DELTA VELOCITY
INITVEL6 VLOAD
R2VEC
STORE RTARG1
INITVEL7 VLOAD VSU
VIPRIME
VINIT
STOVL DELVEET3 # DELVEET3 = VIPRIME-VINIT
(+7)
VTARGET
STORE VTPRIME
SLOAD BHIZ
RTX2
```



Derivation of the Solution to Lamberts Equation

Essentially what we're ultimately looking for is a way to relate time to the true anomaly for a particular orbit.

Lucky this can be done through Kepler's Equation:

$$M = E - e \sin(E)$$

Where:

M is the mean anomaly (should the orbit be circular and not elliptic how far along would we be?)

E is the eccentric anomaly if the orbit were to be an circle where along the path would the true anomaly be

e is the eccentricity

Example Use

$$SMA = 10,000 \text{ km}, t_1 = 0, t_2$$

$$= 2000 \text{ s}$$

$$e = 0.3$$

(1) Find Angular Frequency

$$n = \sqrt{\frac{\mu}{a^3}}$$

$$n = \sqrt{\frac{3.98 * 10^{14}}{10000 * 10^3}}$$

$$n = 6.308 * 10^{-4} \frac{\text{rad}}{\text{sec}}$$

(2) Find Mean Anomaly:

$$M = n(t_2 - t_1)$$

$$M = 1.261 \text{ rad}$$

(3) Using the Bisection method we can solve:

$$2.161 = E - 0.3 * \sin(E)$$

$$E = 1.56 \text{ rad}$$

(4) Now solve for the True Anomaly θ :

$$\theta = \tan^{-1}\left(\frac{\sqrt{1 - e^2} * \sin E}{\cos(E - e)}\right)$$

$$\theta = 1.88 \text{ rad}$$

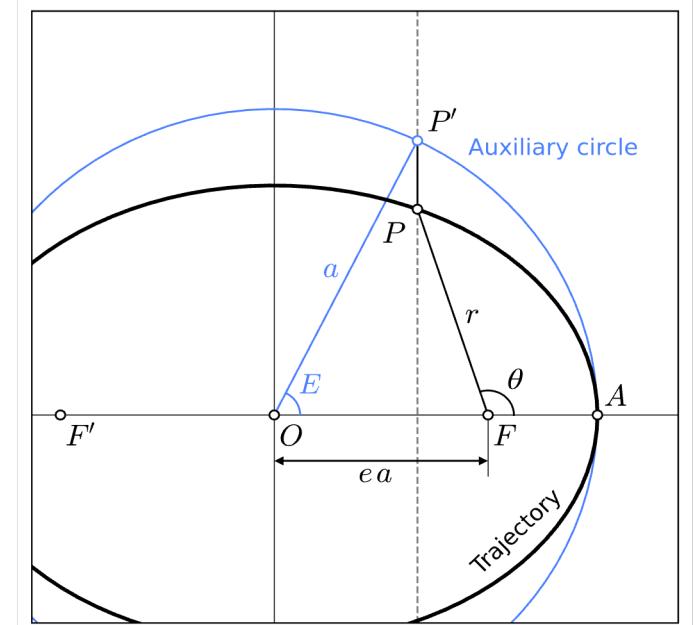
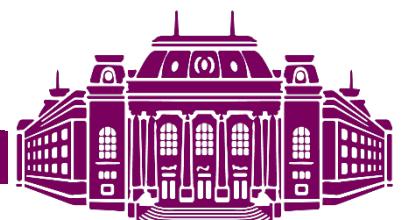


Figure: Mean Eccentricity as it relates to the TA



Derivation of the Solution to Lamberts Equation

Expanding this to two time measurements:

$$M_1 - M_2 = n[t_1 - t_2 - t_{\bar{p}} + t_{\bar{p}}] = E_1 - e * \sin(E_1) - (E_2 - e * \sin(E_2))$$

$$(t_2 - t_1) * \sqrt{\frac{\mu}{a^3}} = E_1 - E_2 - e * \sin(E_1) + e * \sin(E_2)$$

This looks useful but its written in terms of Eccentric Anomaly we only have access to the position vectors.

Thus this must be transformed into a form of *only* $P_1 P_2$ and Δt

This can be done geometrically by finding the cord length C :

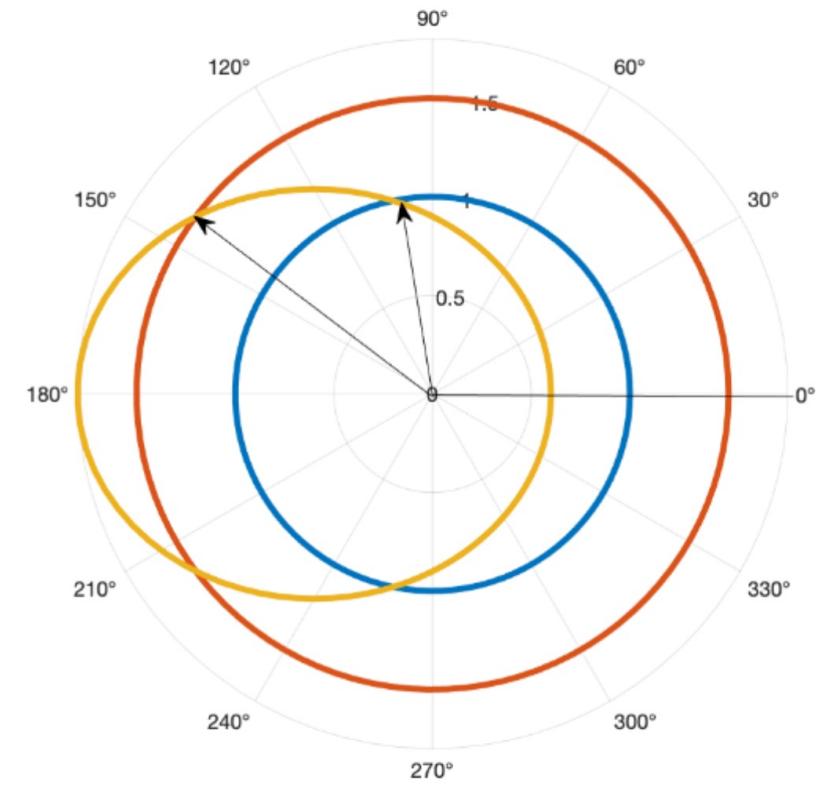
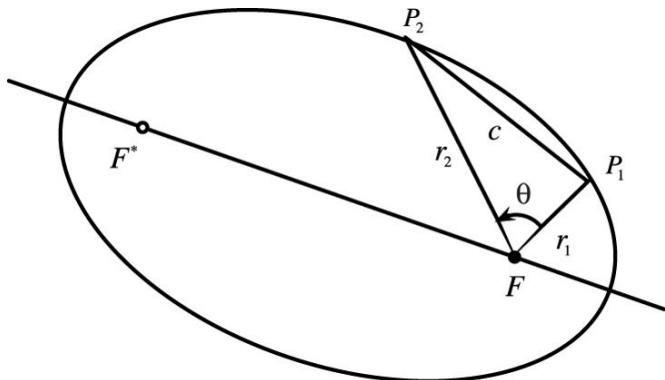


Figure: For given P_1 and P_2 and TOF, the transfer ellipse is uniquely determined.



Derivation of the Solution to Lambert's Equation

Using $r = a(1 - e * \cos(E))$

and using a substitution of $E_p = \frac{E_1 - E_2}{2}$ and $E_M = \frac{E_1 + E_2}{2}$

We find that:

$$r_2 + r_1 = 2a (1 - e \cos(E_p) \cos(E_M))$$

[*] This is powerful because it directly relates the position vectors to its SMA. But this is unsolvable we need another identity to solve for all the variables here

This is done by using the chord distance:

$$c = |(\vec{r}_1 - \vec{r}_2)|$$

$$c^2 = 4a^2 * \sin^2(E_M) * (1 - e^2 * \cos^2(E_p))$$

This can be combined to obtain:

$$r_1 + r_2 + c = 2a (1 - \cos(\alpha)) = 4a * \sin^2\left(\frac{\alpha}{2}\right)$$

And

$$r_1 + r_2 - c = 2a (1 - \cos(\beta)) = 4a * \sin^2\left(\frac{\beta}{2}\right)$$

where:

$$\alpha = \cos^{-1}(e * \cos(E_p)) + E_M$$

$$\beta = \cos^{-1}(e * \cos(E_p)) - E_M$$

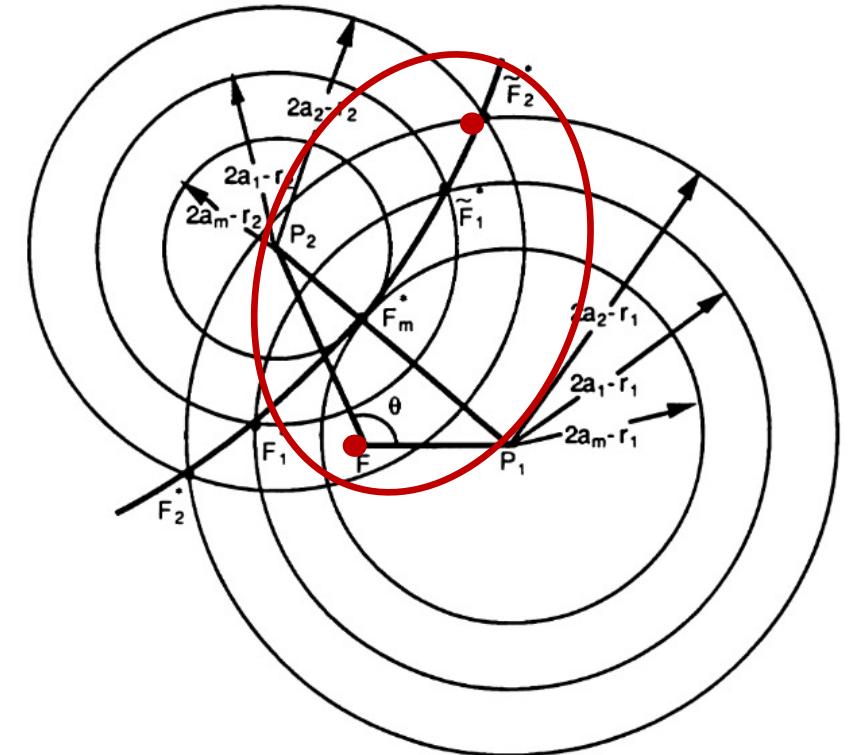


Figure: Geometric Representation of Lambert's Problem and the Role of the Chord Length in Determining the Transfer Orbit



Derivation of the Solution to Lambert's Equation

Going back now to Kepler's Equation:

$$(t_2 - t_1) * \sqrt{\frac{\mu}{a^3}} = E_1 - E_2 - e * \sin(E_1) + e * \sin(E_2)$$

Incorporating the geometric properties into leads to:

$$(t_2 - t_1) * \sqrt{\frac{\mu}{a^3}} = [\alpha - \beta - (\sin\alpha - \sin\beta)]$$

where:

$$\sin\left(\frac{\alpha}{2}\right) = \sqrt{\frac{r_1 + r_2 + c}{4a}}$$

$$\sin\left(\frac{\beta}{2}\right) = \sqrt{\frac{r_1 + r_2 + c - c}{2a}}$$

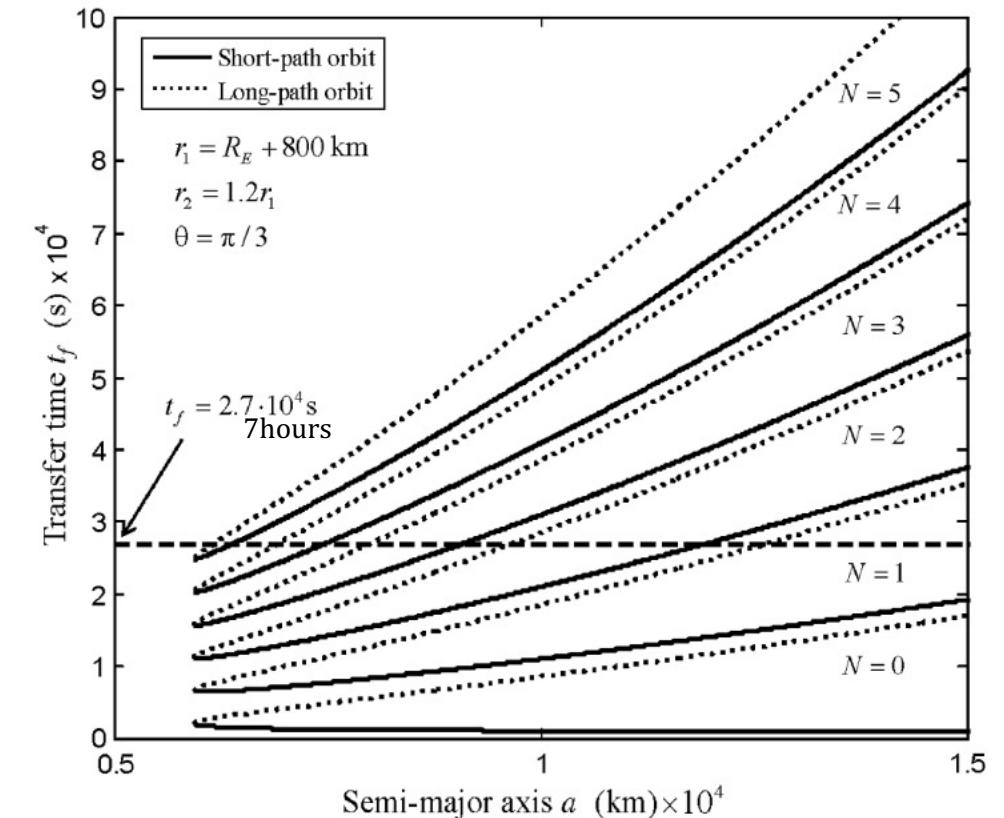


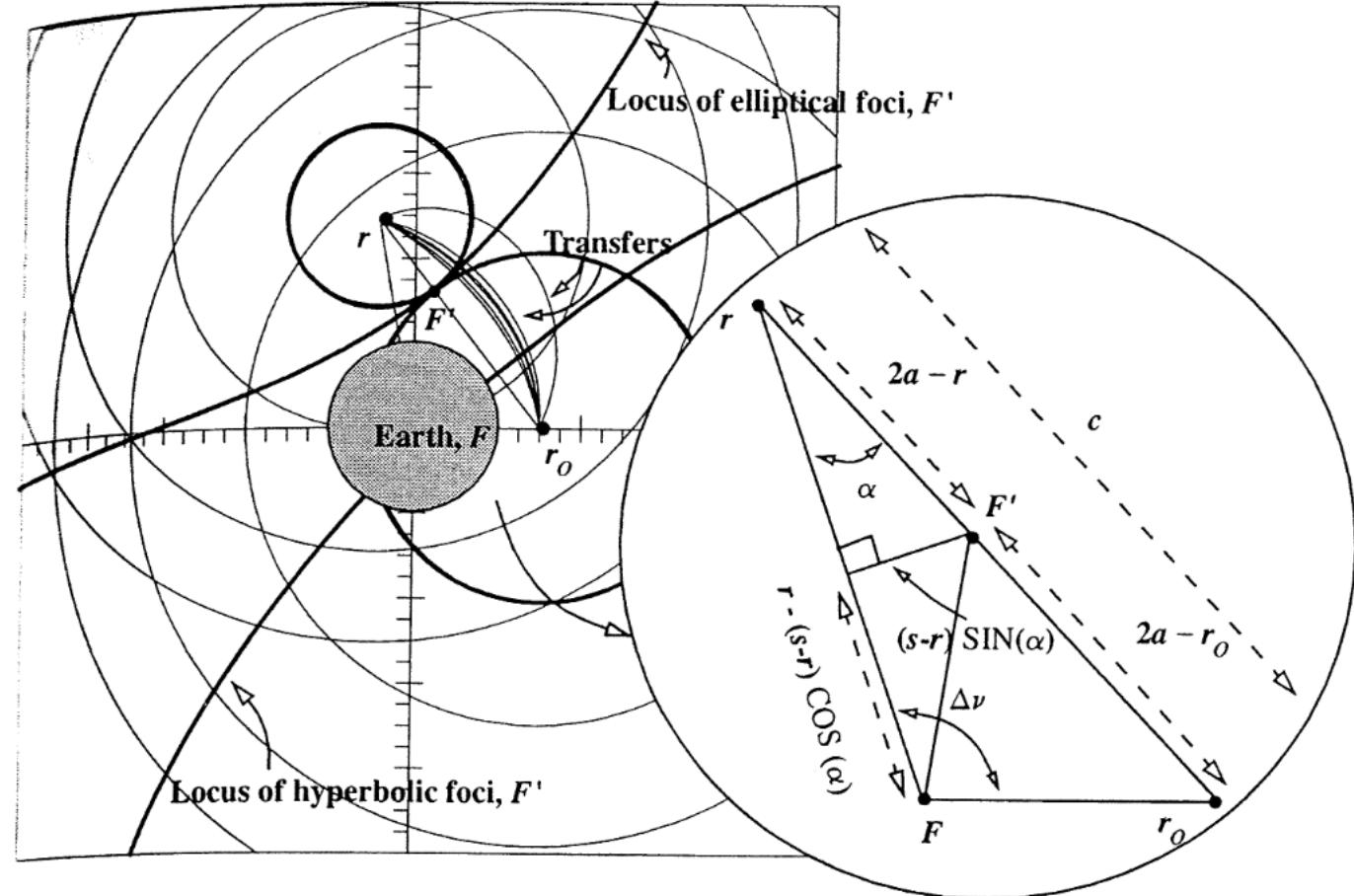
Figure: Solutions to Lambert's Problem including multiple rotations



Methods for the solution to Lambert's Problem

Minimum Energy Transfer:

Hidden focus for the minimum energy transfer lies on the line between r_1, r_2



Numerical Solutions

Using the Universal solution (Battin 1999)

$$C(z) = \begin{cases} \frac{(1-\cos(\sqrt{z}))}{z}, & z > 0 \\ \frac{(\cosh(\sqrt{z})-1)}{z}, & z < 0 \\ \frac{1}{2}, & z = 0 \end{cases} \quad S(z) = \begin{cases} \frac{(\sqrt{z}-\sin(\sqrt{z}))}{(\sqrt{z})^3}, & z > 0 \text{ (Elliptical)} \\ \frac{(\sinh\sqrt{-z}-\sqrt{-z})}{(\sqrt{-z})^3}, & z < 0 \text{ (Hyperbolic)} \\ \frac{1}{6}, & z = 0 \text{ (Parabolic)} \end{cases}$$

$$Y(z) = R_1 + R_2 + A \cdot \frac{zS(z) - 1}{\sqrt{C(z)}}$$

where: R_1 & R_2 are the magnitude of the position vectors
 A is a constant related to the transfer angle and geometry

$$F(z, t) = \left(\frac{C(z)}{Y(z)} \right)^{\frac{3}{2}} * S(z) + A\sqrt{Y(z)} - \mu t$$

Goal: Find a z value such that $F(z, t) = 0$

Solution: Using Newtons Method $z_1 = z_0 - \frac{F(z, t)}{d F(z, t)}$



Earth – Mars Launch Windows

By solving Lambert's problem across a range of departure dates and times of flight, we generate a map of possible trajectories.

From which we optimize for parameters such as the required departure velocity (C_3), arrival velocity, or total mission Δv .

Only in the shaded areas is where a Ballistic maneuver is possible.

Remember Lambert solvers solve using Keplerian motion.

Note: $Departure\ Energy = V_{\infty}^2 (Hyperbolic\ Escape\ Velocity)$

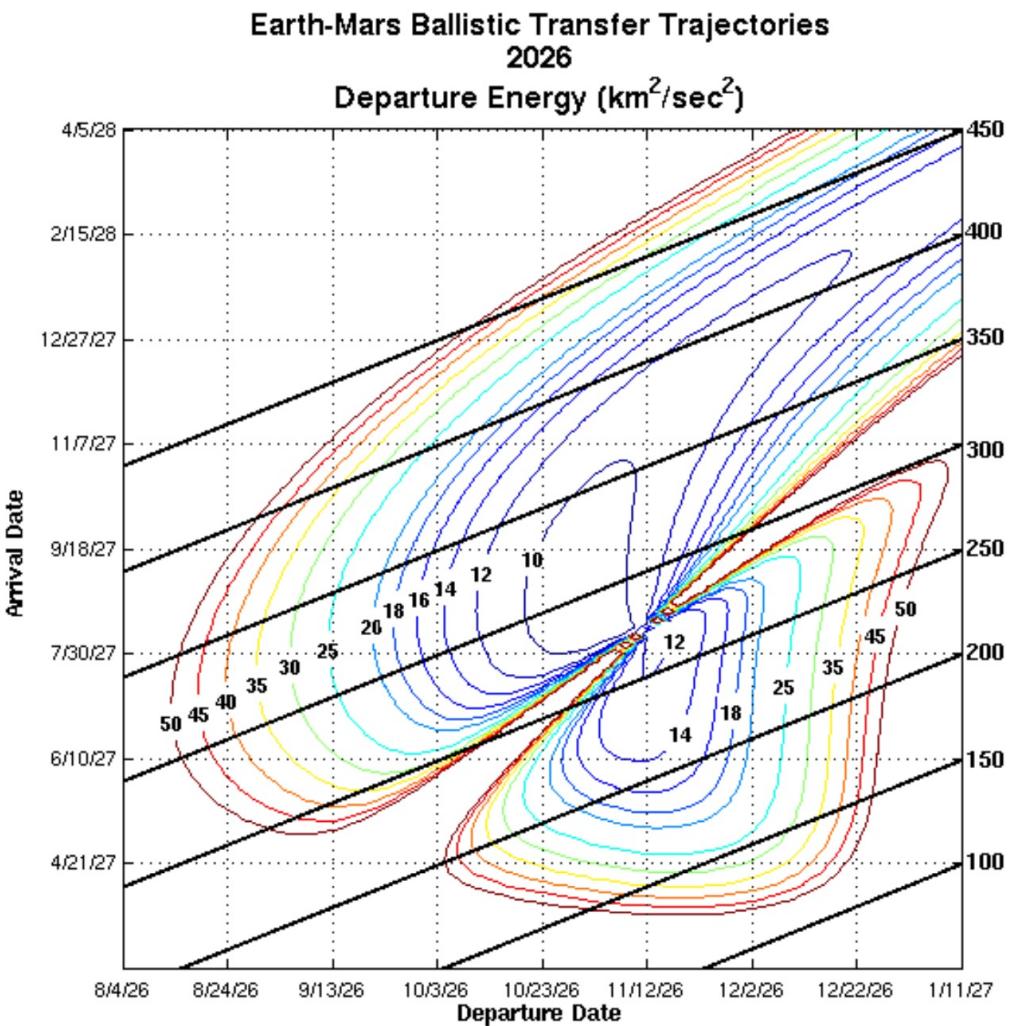
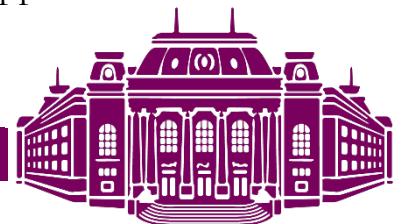


Figure: Porkchop “Interplanetary Mission Design Handbook: Earth-to-Mars Mission Opportunities 2026 to 2045”

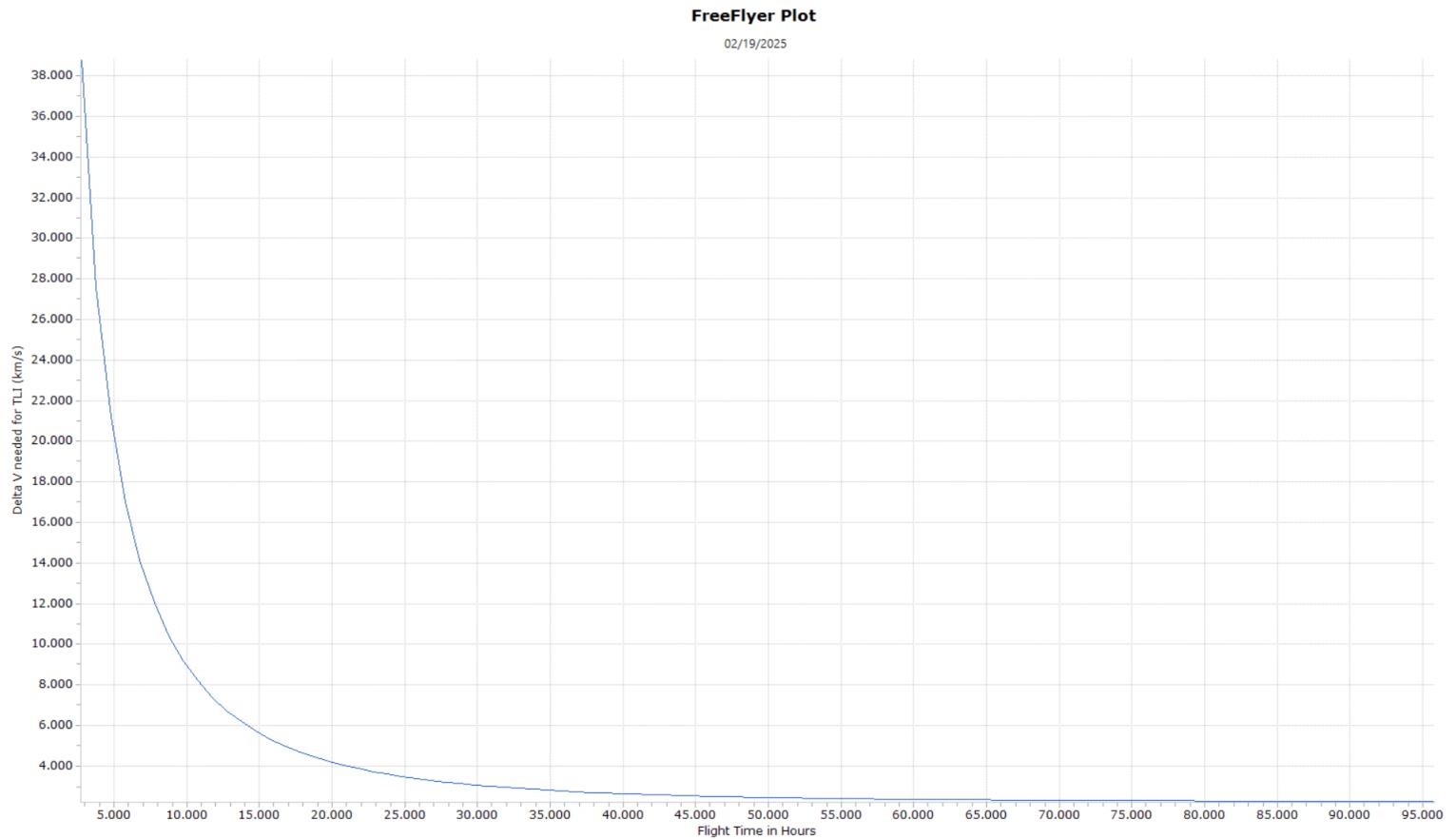


Practical Implementation for the Earth-Moon Transfer

Reduced form of the Porkchop plot as the final date remains fixed – October 28

We see a clear non- linear relationship between the transfer time and required ΔV

In my case I used a transfer time of 96hrs (4days) – Requiring a $\Delta V = 2.257 \frac{km}{s}$



Methods for Entering the Final Orbit

Step 1: Wait until we enter the SOI of the moon

Using the equation: $r_{SOI} = SMA_{Moon} * \left(\frac{m_{Moon}}{M_{Earth}}\right)^{\frac{2}{5}} = 66190.4585 \text{ km}$

Change to Moon Reference frame

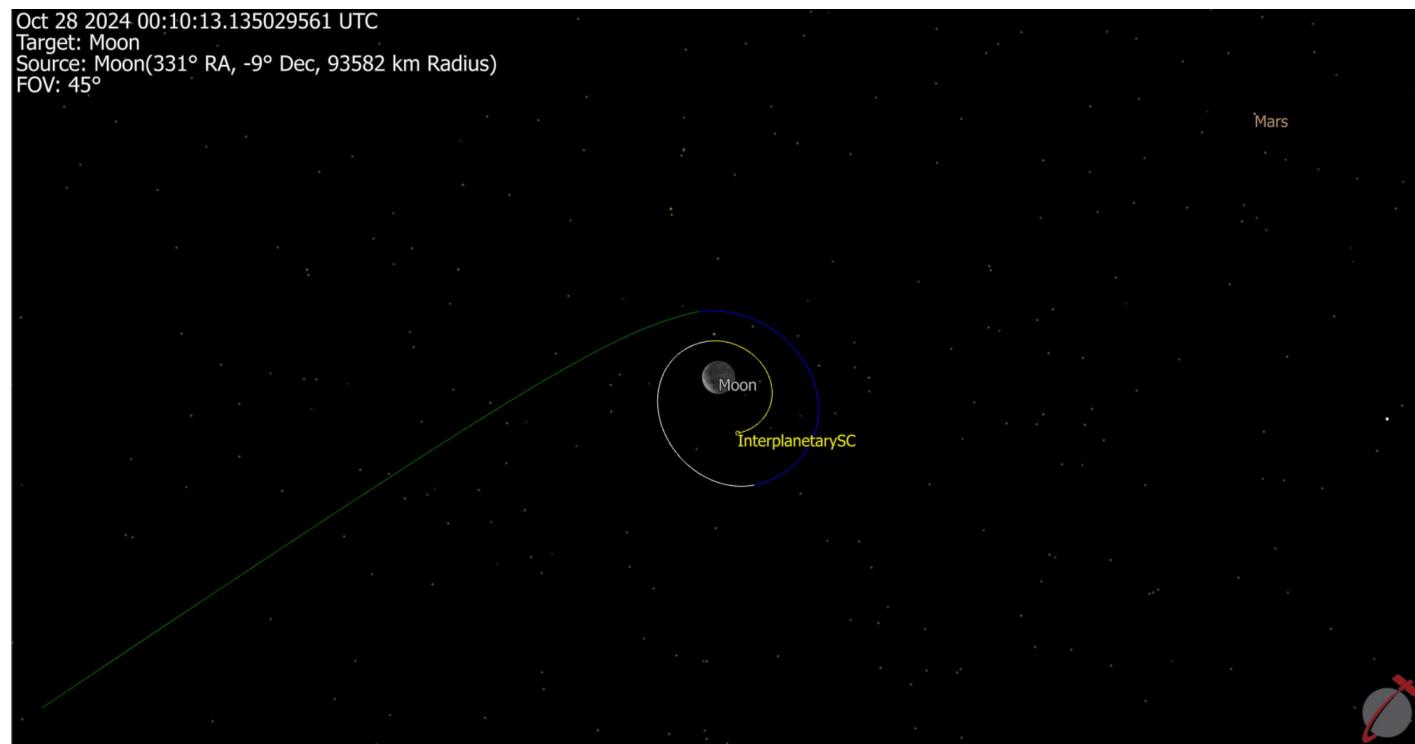
Perform an inclination change to $i = 110^\circ$

Requiring a $\Delta V = 0.499 \frac{\text{km}}{\text{s}}$ Burn #2

Step 2: Continue to Periapsis of Hyperbolic Orbit

Step 3: Perform an insertion burn to enter with an eccentricity of 0.2 from 7.900

Requiring a $\Delta V = 0.781 \frac{\text{km}}{\text{s}}$ Burn #3



Methods for Entering the Final Orbit

Step 4: Step to the new Orbit Apoapsis

Perform a burn to Raise the periapsis to 4400km

Requiring a $\Delta V = 0.171 \frac{km}{s}$ Burn #2

Step 5: Step to the new Orbit Periapsis

Perform a burn to Raise the Apoapsis to 6600km

Requiring a $\Delta V = 0.259 \frac{km}{s}$ Burn #2

$$Total \Delta V = \sum Burns = 3.969 \frac{km}{s}$$

Final Parameters:

Arrival date:

Oct 28 2024 16:39:44.261766156

A: 5510.51 km

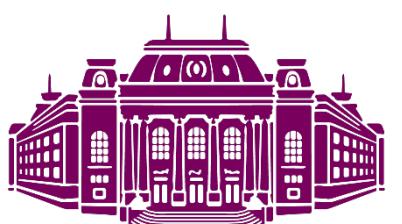
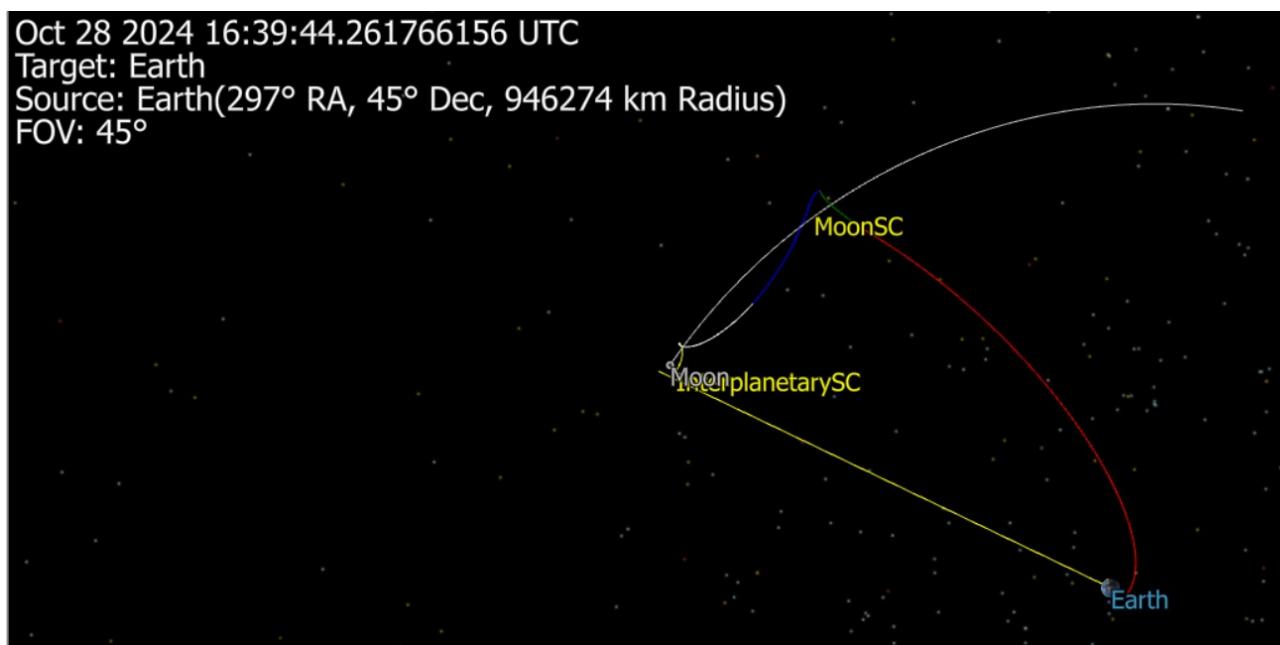
E: 0.197823823

I: 110.19 deg

RAAN: 255.80 deg

W: 64.19 deg

TA: 180.00 deg



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